

Contents

- Foreword V
- Preface of the Editors VII

- 1 The Market for Fieldbus and industrial Ethernet 1**
David Humphrey, Florian Güldner
- 1.1 The Benefits of Being Connected 2
- 1.2 The Market for industrial Ethernet Products 3
- 1.3 Market Players 4

- 2 Trends in Factory Automation 9**
Michael Volz
- 2.1 Growth Factors 10
- 2.2 What Users are Demanding 11
- 2.3 Focus on Engineering Cost 11
- 2.4 Security Aspects 12

- 3 International Standardization 13**
Max Felser
- 3.1 History of Fieldbus Standards 13
 - 3.1.1 The German-French Fieldbus War 13
 - 3.1.2 The International Fieldbus War 14
 - 3.1.3 The Compromise Solution 14
 - 3.1.4 Extensions with Ethernet 16
 - 3.1.5 Extensions with Wireless Systems 16
- 3.2 Structure of Fieldbus Standards 17
 - 3.2.1 Definition of Fieldbuses 17
 - 3.2.2 Definition of Real-time Ethernet 17
 - 3.2.3 Installation Guidelines 18
 - 3.2.4 Reliability 19
 - 3.2.5 Definition of Protocol Families 19
- 3.3 Summary 21

4	Fieldbuses: Status and Outlook	25
	<i>Michael Volz</i>	
4.1	Stability and Reliability as Success Factors	26
4.2	Challenges for the Future	26
4.3	Quality through Certification	27
5	CANopen	29
	<i>Holger Zeltwanger</i>	
5.1	Lower Communication Layers	30
5.2	Higher Communication Layers	32
5.3	Device and Application Profiles	35
5.4	Summary	40
6	CC-Link	41
	<i>John Browett, John Wozniak</i>	
6.1	CC-Link Network Types	42
6.2	CC-Link topology and communication speeds.	43
6.3	Data Transmission.	44
6.3.1	CC-Link Data Types	44
6.3.2	Types of Stations.	45
6.3.3	Maximum Number of Devices.	45
6.3.4	Typical Scan Times	45
6.4	How CC-Link Communicates	48
6.4.1	CC-Link Transmission Processes	48
6.4.2	CC-Link Memory Mapping	50
6.5	Version 1.1 or Version 2.0.	54
6.6	CC-Link Implementation.	55
6.7	Profiles	55
6.8	CC-Link Safety.	57
6.9	Certification Testing.	57
7	CIP: DeviceNet and ControlNet	59
	<i>Viktor Schiffer</i>	
7.1	Basic Elements of the Common Industrial Protocol (CIP)	60
7.1.1	Object Orientation	61
7.1.2	Basic Principles of CIP Communications.	62
7.1.3	Connections, Message Types.	63
7.1.4	Objects	64
7.1.5	Device Profiles.	66
7.1.6	Configuration and Device Description	67
7.1.7	Bridging and Routing.	68
7.1.8	Functional Safety (CIP Safety)	69
7.1.9	Conformance Testing.	71

7.2	DeviceNet	72
7.2.1	Communication Model.	72
7.2.2	System Concepts	73
7.2.3	System Start-up	74
7.2.4	Addressing Principles.	75
7.2.5	Supported Topologies.	75
7.2.6	Data Rates	76
7.2.7	Installation	76
7.2.8	Communication PLC – I/O	77
7.2.9	Communication PLC – PLC	79
7.2.10	Device Configuration and Integration	80
7.2.11	Safety Support	80
7.2.12	Profiles	80
7.2.13	Diagnostics.	80
7.2.14	Device Replacement	81
7.3	ControlNet	81
7.3.1	Communication Model.	81
7.3.2	System Concepts	82
7.3.3	Addressing Principles.	84
7.3.4	Supported Topologies.	84
7.3.5	Data Rates	84
7.3.6	Installation	84
7.3.7	Communication PLC – I/O	86
7.3.8	Communication PLC – PLC	86
7.3.9	Device Configuration and Integration	87
7.3.10	Safety Support	87
7.3.11	Profiles	87
7.3.12	Diagnostics.	87
7.3.13	Device Replacement	88
8	INTERBUS.	91
	<i>Martin Müller</i>	
8.1	Basic Specifications of the INTERBUS System	91
8.1.1	The Ring System.	92
8.1.2	The INTERBUS Elements	93
8.1.3	The INTERBUS Remote Bus.	94
8.2	Data Transmission in the INTERBUS System	95
8.2.1	The Summation Frame Protocol.	95
8.2.2	Data Security in the INTERBUS System	96
8.2.3	Hybrid Data Transmission	96
8.3	INTERBUS Protocol Chips.	97
8.3.1	The IPMS4 Master Protocol Chip	97
8.3.2	The Slave Protocol Chips	97

8.4	INTERBUS Diagnostics.	99
8.4.1	Graded Diagnostic Concept	99
8.4.2	Fiber Optic Diagnostics	101
8.5	INTERBUS Safety	103
8.5.1	Method of Operation	103
8.5.2	Advantages for the User	103
8.6	Conclusion	105
9	PROFIBUS.	107
	<i>Klaus-Peter Lindner</i>	
9.1	Overview: PROFIBUS as Modular System	107
9.2	Transmission Technology.	109
9.2.1	RS485.	109
9.2.2	Optical Transmission	110
9.2.3	MBP	111
9.2.4	Troubleshooting.	112
9.3	Communication	112
9.3.1	Performance Level DP-V0	113
9.3.2	Performance Level DP-V1	115
9.3.3	Performance Level DP-V2	116
9.3.4	Addressing with Slot and Index	116
9.4	General Application Profiles	117
9.4.1	PROFIsafe	117
9.4.2	Redundancy	119
9.5	Specific Application Profiles	120
9.5.1	PROFIdrive	120
9.5.2	Fluid Power	121
9.5.3	Ident Systems	121
9.5.4	PROFIBUS PA.	121
9.6	Device Management.	122
9.7	PROFIBUS Implementation	123
9.8	Quality Assurance and Certification.	123
9.8.1	Test Procedure.	124
10	Comparison of Fieldbus Systems.	127
	<i>Michael Volz</i>	

11	Industrial Ethernet: Status and Outlook	129
	<i>Michael Volz</i>	
11.1	Real-time Behavior	130
11.2	Connection between Office World and Control Technology	131
11.3	Cabling Technology	131
11.4	Outlook	132
12	CC-Link IE	133
	<i>John Browett, John Wozniak</i>	
12.1	CC-Link IE Control	133
12.2	CC-Link IE Field	134
12.2.1	CC-Link IE Field Topology	134
12.2.2	CC-Link IE Field Data Types and Network Memory Allocation	137
12.2.3	CC-Link IE Field Communication	139
12.2.4	CC-Link IE Field Frame Structure	144
12.2.5	Connection for Ethernet TCP/IP (UDP/IP) Devices	145
12.2.6	CC-Link IE Field Implementation	145
12.2.7	Profiles	146
12.2.8	CC-Link Conformance Testing	148
12.2.9	Main features of CC-Link IE Field	148
13	EtherCAT	149
	<i>Oliver Fels</i>	
13.1	Technology Principle	150
13.1.1	Processing „on the fly“	150
13.1.2	Best Performance	150
13.1.3	Migration from Classical Fieldbus to EtherCAT with Gateways	151
13.1.4	Flexible Topology Including Redundancy Options	152
13.1.5	Easy Diagnosis and Configuration	154
13.1.6	Use of Standard Components	154
13.2	The EtherCAT Device Protocol	155
13.2.1	Cyclic Communication (Process Data)	156
13.2.2	Acyclic Communication	156
13.2.3	Synchronization with Distributed Clocks (DC)	158
13.3	Integrated Functional Safety	159
13.4	EtherCAT for Plant Automation	162
13.5	Implementation Aspects	165
13.5.1	Master Implementation	165
13.5.2	Slave Implementation	166
13.5.3	Monitoring Tools	166
13.6	EtherCAT Technology Group	167

14	EtherNet/IP	171
	<i>Viktor Schiffer</i>	
14.1	Communication Model	172
14.2	System Concepts	172
14.3	Addressing Principles	174
14.4	Supported Topologies	174
14.5	Data Rates	175
14.6	Installation	175
14.7	Communication PLC – I/O.	176
14.8	Communication PLC – PLC	177
14.9	Device Configuration and Integration	177
14.10	Safety Support	178
14.11	Profiles	178
14.12	Diagnostics	178
14.13	Device Replacement	178
14.14	Fieldbus Integration	179
14.15	Integration in Enterprise Networks	179
14.16	Security	180
15	Modbus	183
	<i>Michael Volz</i>	
15.1	History of the Modbus Protocol	183
15.2	The Modbus Protocol Suite.	184
15.3	Modbus TCP Overview.	184
	15.3.1 Modbus Protocol Function Codes.	185
	15.3.2 The Modbus application data unit (ADU)	187
	15.3.3 Modbus TCP Addressing Model.	188
	15.3.4 Modbus TCP Data Model	188
	15.3.5 Modbus Protocol Transactions	189
	15.3.6 Modbus PDU and ADU Formats	190
	15.3.7 Modbus Exception Responses	191
15.4	Mapping the Modbus Protocol on TCP/IP	193
	15.4.1 Modbus TCP Connection Management	194
	15.4.2 Use of TCP/IP Stack.	194
15.5	Configuration of Modbus TCP devices and systems.	196
15.6	Performance Aspects	196
15.7	Modbus TCP Conformance Testing.	197
15.8	The Modbus Organization	197
16	POWERLINK	199
	<i>Stefan Schönegger</i>	
16.1	Data Exchange with POWERLINK	200
	16.1.1 Why Standard Ethernet cannot Achieve Hard Real-time Operation	200

16.1.2	The POWERLINK Stack	201
16.1.3	The POWERLINK Mechanism	202
16.2	Functional Characteristics of POWERLINK	203
16.2.1	Network Structure with POWERLINK: Free Selection of Topology	203
16.2.2	Unique Addressing for each Node.	204
16.2.3	Hot Plugging.	204
16.2.4	Cross-traffic Increases Performance and Simplifies the System	205
16.2.5	Redundant Networks with POWERLINK	206
16.2.6	Diagnostics.	206
16.2.7	POWERLINK = CANopen over Ethernet	207
16.3	Safety and Security	207
16.3.1	Bus Independence.	208
16.3.2	openSAFETY Functionality	209
16.3.3	Mechanisms for Error Detection and Prevention	209
16.3.4	Structure of the openSAFETY Frame	210
16.3.5	The openSAFETY Network	210
16.3.6	Security.	211
16.4	Technical Implementation of the Master and Slaves	211
16.4.1	Solutions for the POWERLINK Master.	212
16.4.2	Solutions for the POWERLINK Slave.	212
16.5	POWERLINK Open Source	213
16.6	EPSP User Organization	213
17	PROFINET	215
	<i>Jörg Freitag</i>	
17.1	PROFINET at a Glance	216
17.1.1	PROFINET Highlights	217
17.1.2	PROFINET IO Device Classes.	217
17.1.3	Addressing in PROFINET IO	218
17.2	PROFINET IO Basics	219
17.2.1	Device Model	219
17.2.2	Real-time Communication.	220
17.2.3	Data Communication.	221
17.2.4	Network Diagnostics in PROFINET	222
17.2.5	System Engineering and GSD	223
17.2.6	System Power-up	223
17.2.7	Neighborhood Detection.	224
17.2.8	Fast Start-up	224
17.3	IRT Communication in PROFINET IO.	225
17.3.1	IRT Control	225
17.3.2	IRT Intervals.	226
17.4	PROFINET IO Controller and Device	227

17.5	Conformance Classes (CC)	227
17.6	Application Profiles for PROFINET IO	228
	17.6.1 Train Applications.	228
	17.6.2 PROFIenergy	228
17.7	Integration of Fieldbus Systems	230
17.8	Network Installation.	230
	17.8.1 PROFINET Cabling.	231
	17.8.2 Plug Connectors for Data	232
	17.8.3 Plug Connectors for Power.	232
	17.8.4 Network Components	232
	17.8.5 Redundancy	232
	17.8.6 Industrial Wireless	233
17.9	PROFINET IO Certification	234
18	sercos	235
	<i>Peter Lutz</i>	
18.1	sercos I and II	235
	18.1.1 Topology	236
	18.1.2 Communication Method, Synchronization and Protocol Structure.	237
	18.1.3 Standardized Data.	239
	18.1.4 Implementation	240
18.2	sercos III	240
	18.2.1 Topology and Installation	240
	18.2.2 Transmission Procedure	241
	18.2.3 Message Structure.	243
	18.2.4 Ring Redundancy and Hot-Plugging	243
	18.2.5 Direct Cross Communication and Controller-to-Controller Communication (C2C)	243
	18.2.6 Synchronization	244
	18.2.7 CIP Safety on sercos.	245
	18.2.8 Device Profiles.	246
18.3	Implementation of sercos III	248
18.4	Summary	249
19	Comparison of Ethernet Systems.	251
	<i>Frithjof Klasen</i>	
19.1	Performance Indicators	251
19.2	Requirements	252
19.3	Implementation Concept	254
19.4	Selection Criteria	256
19.5	Future Outlook.	258

20	Wireless: Status and Outlook	259
	<i>Lutz Rauchhaupt</i>	
20.1	Wireless, Radio, or WLAN	259
20.2	Requirements and Conditions of Radio-based Industrial Communication	260
20.3	Cellular Network Systems.	261
20.4	Wireless Local Area Networks (WLAN)	263
20.5	Bluetooth	265
20.6	WirelessHART	266
20.7	Wireless Sensor/Actor Network for Factory Automation (WSAN-FA)	267
20.8	Other Wireless Solutions	268
20.9	Outlook.	269
21	Connecting Networks	271
	<i>Michael Volz</i>	
21.1	Connection of Autonomous Plant Units having their Own PLCs	271
21.2	Connection of Lower-level Plant Units without Own PLCs.	273
21.3	Selection and Use Criteria	273
22	Security for Ethernet Systems	275
	<i>Frithjof Klasen</i>	
22.1	Industrial Ethernet Affects Security Solutions	275
22.2	Challenges	276
	22.2.1 Organizational Challenges	277
22.3	Differences to Business IT	277
22.4	Technical Challenges	278
22.5	Possible Solutions	279
	22.5.1 Security Objectives	280
	22.5.2 Threats and Risk Analysis	280
	22.5.3 Security – A Joint Project.	280
22.6	The Solution: People, Processes, Technologies	281
23	Field Device Integration with FDI	283
	<i>Daniel Großmann, Alexander Kaiser</i>	
23.1	Current Situation in Device Integration.	283
23.2	The Solution: Field Device Integration	284
	23.2.1 Benefits of EDDL	284
	23.2.2 Benefits of FDT	284
23.3	Device Package – Representative for a Device	285
	23.3.1 Catalog (mandatory)	285
	23.3.2 EDD – Device Definition – DEF (mandatory, based on EDDL)	286

23.3.3	EDD – User Interface Description – UID (mandatory, based on EDDL)	286
23.3.4	EDD – Business Logic – BL (mandatory, based on EDDL and FDT)	286
23.3.5	User Interface Plug-in – UIP (optional, based on FDT).	286
23.3.6	Attachments (mandatory; optional – depending on protocol)	287
23.4	The Basic Architecture	287
23.4.1	System Architectures	288
23.4.2	Topologies	289
23.5	Aiming for a Uniform Approach through Harmonization	291
23.6	FDI from an End User Perspective.	293
23.6.1	A Solution	293
23.6.2	Safeguarding Investments	294
23.6.3	Robustness	294
23.6.4	Interoperability	294
23.6.5	Uniformity	295
23.6.6	Version Handling	295
23.7	Summary	295
24	Implementation Criteria: Make or Buy?	297
	<i>Volker Oestreich</i>	
24.1	Market Situation	297
24.2	Options for Implementation	298
24.2.1	In-House Development of Communication Interfaces	298
24.2.2	In-house Development with External Support.	298
24.2.3	Application of Modular Communication Modules	299
24.3	The Right Decision: Assistance Offered.	299
24.3.1	Example: Tightening Controller.	301
24.3.2	Specified Boundary Conditions	301
24.3.3	Results of the Calculation	302
24.4	Conclusion	303
25	Flexible Interface Implementation.	305
	<i>Michael Volz</i>	
25.1	Development Planning	305
25.1.1	Consultation	305
25.1.2	Implementation	306
25.1.3	Development Environment	306
25.1.4	Hardware/Software Design.	306
25.1.5	Certification	306
25.1.6	Technology Support.	307

25.2 In-house Development or Development Partnership 307

25.2.1 Implementation Options 308

25.2.2 In-house Development of Communication Interfaces 308

25.2.3 Customer-specific Solutions 309

25.2.4 Ready-to-use Communication Modules 309

25.2.5 External Bus Connection with a Protocol Converter 310

Organizations 312

Authors 317

Index 327

