

Program

A1: Medical Devices / Medical Engineering

Chairs: Peter P. Pott (Universität Stuttgart, Germany), Bert Müller (University of Basel, Switzerland)

***Characterization of a soft magnetic catheter controlled by a permanent magnet* 1**

Mohammad Hasan Dad Ansari (Scuola Superiore Sant'Anna & KU Leuven, Italy);
Xuan Thao Ha (Katholieke Universiteit Leuven, Belgium); Mouloud Ourak (KU Leuven,
Belgium); Veronica Iacovacci (Scuola Superiore Sant'Anna, Italy); Gianni Borghesan
(Katholieke Universiteit Leuven, Belgium); Emmanuel Benjamin Vander Poorten (KU
Leuven, Belgium); Arianna Menciassi (Scuola Superiore Sant'Anna, Italy)

***Miniature Pneumatic Artificial Muscles for Use in Surgical Devices* 4**

Bob Lathrop (KU Leuven, Belgium); Mouloud Ourak (KU Leuven, Belgium);
Emmanuel Benjamin Vander Poorten (KU Leuven, Belgium)

***Discrete bistable-actuated catheter* 8**

Emmanuel Benjamin Vander Poorten and Julie Legrand (KU Leuven, Belgium);
Mouloud Ourak (KU Leuven, Belgium)

***A manually actuated continuum robot research platform for deployable shape-memory curved cannulae in stereotactic neurosurgery* 10**

Julian Mühlenhoff and Thorben Körbner (Technische Universität Ilmenau, Germany);
Giovanni Miccoli, Dörthe Keiner and Matthias K. Hoffmann (Saarland University, Germany);
Philipp Sauerteig and Karl Worthmann (Technische Universität Ilmenau, Germany);
Kathrin Flaßkamp, Steffi Urbschat and Joachim Oertel (Saarland University, Germany);
Thomas Sattel (Technische Universität Ilmenau, Germany)

B1: Polymer Actuators

Chair: Aaron Price (Western University, Canada)

***Boron-based magnetoactive Polymers - the new smart material* 14**

Gareth Monkman and Maximilian Schirmer (OTH Regensburg, Germany);
Christoph Putz and Robert Sattler (OTH-Regensburg, Germany)

***Continuous, highly efficient production of twisted monofilaments for twisted coiled polymer actuators* 18**

Johannes Mersch (Technische Universität Dresden, Germany); Nicholas Witham
(University of Utah, USA); Markus Koenigsdorff (Technische Universität Dresden, Germany);
Florian Solzbacher (University of Utah, USA); Gerald Gerlach (Technische Universität
Dresden, Germany)

***Design of Electrical Contact for DE Transducers under Thermal Considerations* 21**

Michael J. Gareis, Ozan Çabuk and Jürgen Maas (Technische Universität Berlin,
Germany)

C1: Optics

Chair: Barkan Ugurlu (Ozyegin University, Turkey)

***Fabrication of Micro Halbach Arrays in a Monolithic Ring Magnet by Laser-Assisted Heating Magnetization* 25**

Keita Nagai and Youhei Hamaoka (Tokyo Institute of Technology, Japan); Naohiro Sugita (Tokyo Institute of Technology); Tadahiko Shinshi (Tokyo Institute of Technology, Japan)

***Concept for an SMA-Actuated Camera Gimbal*..... 27**

Alexander Schwegler and Arif Kazi (Aalen University of Applied Sciences, Germany); Tobias Schumm and Markus Koepfer (Actuator Solutions GmbH, Germany)

***Development of a SMA driven articulation and autofocus mechanism for endoscope applications*..... 31**

Michele Mandolino and Rouven Britz (Saarland University, Germany); Yannik Goergen (ZeMA gGmbH & Saarland University, Germany); Gianluca Rizzello (Saarland University, Germany); Paul Motzki (ZeMA gGmbH & Saarland University, Germany)

***P-FSM150S Fast Steering Mirror for Optical Space Constellations* 35**

Gerald Aigouy and Etienne Betsch (Cedrat Technologies, France); Frank Claeysen (CEDRAT Technologies S.A., France); Adrien Guignabert, Hugo Gardel, Augustin Bedek, Anthony Baillus, Nicolas Bourgeot and Pierre Personnat (Cedrat Technologies, France)

A2: Microfluidic Handling / Energy Harvester

Chairs: Ulrike Wallrabe (Albert-Ludwigs-Universität Freiburg, Germany), Jérôme Perret (Haption GmbH, Germany)

***A Disposable Electromagnetic Micropump for Oscillatory-flow PCR Microfluidic System*... 41**

Chao Qi, Naohiro Sugita and Tadahiko Shinshi (Tokyo Institute of Technology, Japan)

***Development of a Lightweight, Compact and Energy Efficient Pinch Valve driven by Shape Memory Alloy Wires* 43**

Dominik Scholtes (Saarland University & ZeMA gGmbH, Germany); Yannik Goergen (ZeMA gGmbH & Saarland University, Germany); Rouven Britz (Saarland University, Germany); Paul Motzki (ZeMA gGmbH & Saarland University, Germany)

***Media-separated micropump consisting of magnetic shape memory alloy actuator* 47**

Tim Polley, André Harmel, Thomas Weisener and Gerald Vögele (HNP Mikrosysteme GmbH, Germany)

***The energy harvesting system by using internal acoustic energy at both side excitation* ... 51**

M. Tsuchiya, H. Tsuchiya, Hiroyuki Moriyama, H. T. Uchida, Soshi Nagasaka and Yuto Suzuki (Tokai University, Japan)

B2: Electromagnetic Actuators / Magnetostrictive Actuators

Chairs: Wolfgang Amrhein (ACCM GmbH, Austria), Roland Keller (Dr. Fritz Faulhaber GmbH & Co. KG, Germany)

***Self-sensing Giant Magnetostrictive Actuator with Real-time Detection of Mechanical Stress*..... 55**

Dongjian Xie, Yahui Zhang, Haomin Wu, Yikun Yang and Bintang Yang (Shanghai Jiao Tong University, China)

<i>Development of a magnetic reluctance force actuator for chatter suppression in boring bars</i>	59
Fagher Wahab, Asier Astarloa and Iker Mancisidor (Ideko - Member of BRTA, Spain); Maria Fernandes (University of Basque Country (UPV-EHU), Spain); Iñigo Etxaniz and Jokin Munoa (Ideko - Member of BRTA, Spain)	
<i>Design and investigation of a miniaturized tubular electrical linear motor</i>	63
Bela Schulte Westhoff and Jürgen Maas (Technische Universität Berlin, Germany)	
<i>A Comparison of Linear and Circular Force Inertial Actuation</i>	67
Mark Norris (Parker Lord, USA); Larry D Ridge and Brad Sanderson (GHSP, USA); Stefan Barbulescu (Parker Lord, USA)	

C2: Aerospace

Chairs: Frank Claeysen (CEDRAT Technologies S.A., France), Hans Peter Monner (German Aerospace Center (DLR), Germany)

<i>High power density Piezo motors for critical environments</i>	71
Nabil Bencheikh, Alexandre Pagès, Etienne Betsch and Jolan Gauthier (Cedrat Technologies, France)	
<i>SYNJET3C Improvement of Synthetic Jet Actuator Technology for High Efficiency</i>	76
Gerald Aigouy and Arnaud Barnique (Cedrat Technologies, France); Frank Claeysen (CEDRAT Technologies S.A., France); Frederic Ternoy (Onera, France); Martin Schueller (Trisitec, Germany); Eberhard Kaulfersch (Fraunhofer Institute for Electronic Nano Systems, Germany)	
<i>Bio-Inspired Flapping Wing Antagonist Actuation with SMA Wires</i>	81
Domenico Bevilacqua (Saarland University & ZeMA GmbH, Germany); Giovanni Soletti (Politecnico di Bari, Italy); David Naso (Polytechnic University of Bari, Italy); Gianluca Rizzello (Saarland University, Germany); Paul Motzki (ZeMA gGmbH & Saarland University, Germany)	
A3: Robotics	
Chairs: Pierre Renaud (University of Strasbourg, France), Emmanuel Benjamin Vander Poorten (KU Leuven, Belgium)	
<i>Highly dynamic robotic leg for non-biomimetic walking robots</i>	85
Jan Baumgärtner (Zentrales Institut Für Informatik, Universität Heidelberg, Germany); Johannes Bach (Institut Für Medizingerätetechnik, Universität Stuttgart, Germany); Lorenzo Masia (Zentrales Institut Für Informatik, Universität Heidelberg, Germany); Essameddin Badreddin (Institute for Computer Engineering, University of Heidelberg, Germany); Peter P. Pott (Universität Stuttgart, Germany)	
<i>A Servomotor with Adjustable Stiffness for Humanoid Robotics Application</i>	89
Michele Folgheraiter, Timur Umurzakov and Sharafatdin Yessirkepov (Nazarbayev University, Kazakhstan)	
<i>Design and Parameter Identification of a Soft Robotic bendable module with Artificial Muscle Fibers</i>	93
Matthias Baltes and Johannes Prechtel (Saarland University, Germany); Julian Kunze (Saarland University & ZeMA, Germany); Gianluca Rizzello (Saarland University, Germany)	

<i>Anisotropic Carbon Fibre Electrodes for Dielectric Elastomer Actuators</i>	97
Markus Koenigsdorff, Johannes Mersch, Sascha Pfeil and Gerald Gerlach (Technische Universität Dresden, Germany)	
B3: Actuators Based on ER/MR Fluids	
Chairs: Janusz Goldasz (BWI Group, Technical Center Krakow, Poland), Jürgen Maas (Technische Universität Berlin, Germany)	
<i>A compact 4-DoF MR damper with independent damping adjustment</i>	101
Aditya Suryadi Tan, Fabian Rabel and Yannick Lee Sill (Technische Universität Ilmenau, Germany); Thomas Sattel (Ilmenau University of Technology, Germany)	
<i>The transient response of magnetorheological actuator/ fluid in shear mode on the rapid change of magnetic field: effect of shear rate</i>	105
Josef Válek, Michal Kubík, Ondrej Machacek and Zbyněk Strecker (Brno University of Technology, Czech Republic)	
<i>Development of a precisely controlled magnetorheological fluid brake for medical ergometers</i>	109
Lukas Masjosthusmann and Valentin Schreiner (Technical University Berlin, Germany); Julian Tschersich and Frank Baumann (Maschinenfabrik Mönninghoff GmbH Co. KG, Germany); Lutz Neumann (Ergoline GmbH, Germany); Jürgen Maas (Technische Universität Berlin, Germany)	
<i>Online rotor balancing by weight spheres controlled by magnetorheological fluids</i>	113
Valentin Schreiner (Technical University Berlin, Germany); Jürgen Maas (Technische Universität Berlin, Germany)	
C3: Industrial Applications	
Chairs: Miriam Biedermann (Bürkert Werke GmbH & Co. KG, Germany), Hans-Jürgen Karkosch (Contitech Vibration Control GmbH, Germany)	
<i>MICA20CS PROOF MASS ACTUATOR</i>	117
Gérald Aigouy, Xavier De Lepine, Patrick Meneroud, Steven Rowe, Aurore Piéton, Théo Simon, Marc Fournier and Olivier Sosnicki (Cedrat Technologies, France); Frank Claeysen (CEDRAT Technologies S.A., France)	
<i>High performance four-quadrant actuator</i>	122
Wolfgang Zoels, Georg Bachmaier and Christopher McClanahan (MetisMotion GmbH, Germany)	
<i>Mechatronic piezo mechanisms for active vibration control</i>	125
Steven Rowe, Jolan Gauthier, Alexandre Pagès and Jean-Marc Nwesaty (Cedrat Technologies, France)	
<i>Covering a Wide Range of Requirements in Warp Knitting Machines with Modular Actuator Systems and Model-Based System Design</i>	129
Florian Hoppe, Georg Kraus and Christian Arnold (KARL MAYER STOLL R&D GmbH, Germany)	

Plenary Talks

Chairs: Emmanuel Benjamin Vander Poorten (KU Leuven, Belgium), Ulrike Wallrabe (Albert-Ludwigs-Universität Freiburg, Germany)

Recent advances in magnetic shape memory material and device technologies

Markus Laufenberg and Emmanouel Pagounis (ETO MAGNETIC GmbH, Germany)

Fast & fine Steering Mirrors based on piezoelectric & magnetic actuator technologies

for Air & Space..... 132

Frank Claeysen (CEDRAT Technologies S.A., France)

Advances in the Dynamics of Magnetorheological Actuators..... 138

Zbyněk Strecker and Michal Kubík (Brno University of Technology, Czech Republic)

A4: SMA (1)

Chairs: Luigi Manfredi (University of Dundee, United Kingdom (Great Britain)), Giorgio Vergani (SAES Getters S.p.A., Italy)

Evaluation of efficient and lifetime optimised SMA actuation strategies 142

Christoph Dünn, Romina Krieg, Ralf Theiß and Peter Dültgen (Forschungsgemeinschaft Werkzeuge und Werkstoffe e. V.)

Fatigue behavior of Shape Memory Alloy wires actuated at high speed..... 146

Marco Citro and Salvatore Coco (Saes Getters, Italy)

Inverted Pendulum-Type SMA Actuator..... 150

Arif Kazi (Aalen University of Applied Sciences, Germany); Markus Bäuml and Markus Koepfer (Actuator Solutions GmbH, Germany); Tobias Ehrmann (Aalen University of Applied Sciences, Germany)

Analysis of the impact of mechanical guidance on active MSM-stick elongation

behaviour..... 154

Marco Hutter and Bernd Gundelsweiler (University of Stuttgart, Germany)

Enhancing the dynamics of SMA actuators by using latent heat..... 158

Roland Binninger and Daniel Schwarz (Fraunhofer IPM, Germany); Daniel Maiwald and André Bucht (Fraunhofer IWU, Germany); Christian Weck (Fraunhofer IFAM, Germany); Kilian Bartholomé and Olaf Schäfer-Welsen (Fraunhofer IPM, Germany)

B4: Actuator Control and Electronics

Chairs: Jürgen Maas (Technische Universität Berlin, Germany), Waldemar Spomer (Physik Instrumente (PI) GmbH & Co. KG, Germany)

Intelligent force-controlled miniature gripper driven by magnetic shape memory alloy..... 162

Julius Happel, René Schnetzler and Markus Laufenberg (ETO MAGNETIC GmbH, Germany)

Effect of rotor elasticity on driving characteristics of the ultrasonic motors..... 166

Tatsuki Sasamura, Abdullah M Mustafa, Susumu Miyake (The University of Tokyo, Japan), Norio Sashida (SHINSEI CORPORATION) and Takeshi Morita (The University of Tokyo, Japan)

<i>Small and scalable high voltage push-pull converter for feeding dielectric elastomer transducers (DET).....</i>	170
Samuel Junglas and Andreas Hubracht (Technical University of Berlin, Germany); Jürgen Maas (Technische Universität Berlin, Germany)	
<i>Efficient Driving Method for Piezoelectric Inertia Motors</i>	174
Burhanettin Koc (Physik Instrumente (PI) GmbH & Co. KG, Germany); Sebastian Kist and Ammar Hamada (Physik Instrumente (PI), Germany)	
<i>A Planar Single-Actuator Bi-Stable Mechanical/Electrical Switch.....</i>	178
Shuangwen Xie (Tsinghua University, China); Ruizi Liu (The Hong Kong University of Science and Technology, China); Shuya Okayama and Toshiyuki Tsuchiya (Kyoto University, Japan); Man Wong (The Hong Kong University of Science and Technology, China); Xiaohong Wang (Tsinghua University, China)	
 C4: KOMMMA Session (1)	
Chair: Manfred Kohl (Karlsruher Institut für Technologie (KIT), Germany)	
<i>Design of an Liquid Dielectrophoresis driven Platform with Cooperative Actuation</i>	182
Peter Conrad, Andrii Berdnykov and Martin Hoffmann (Ruhr-Universität Bochum, Germany)	
<i>A thermomechanically fully coupled finite strain shape memory alloy model applied to bistable microactuators</i>	
Marian Sielenkämper (Christian-Albrechts-Universität zu Kiel, Germany); Stephan Wulfinghoff (Kiel University, Germany)	
<i>Development of Bimorph and Trimorph Microactuators Based on TiNiHf Thin Film and Si Technology</i>	
Gowtham Arivanandhan and Zixiong Li (Karlsruhe Institute of Technology, Germany); Sabrina Curtis (Kiel University, Germany); Eckhard Quandt (Christian-Albrechts-Universität zu Kiel, Germany); Manfred Kohl (Karlsruher Institut für Technologie (KIT), Germany)	
<i>Study of the Dynamic Behavior of an Electrostatic Actuation Unit Cell for a Cooperative, Bidirectional Inchworm Motor: Design, Fabrication and Characterization</i>	
Almothana Albukhari (Hochschule Furtwangen & University of Freiburg, Germany); Ulrich M. Mescheder (Hochschule Furtwangen, Germany)	
<i>Modeling and Parameter Study of a Cooperative Flexible Array of Dielectric Elastomer Actuators.....</i>	186
Sipontina Croce and Julian Neu (Saarland University, Germany); Jonas Hubertus (University of Applied Sciences of Saarland, Germany); Günter Schultes (HTWsaar, ZeMA gGmbH, Germany); Gianluca Rizzello (Saarland University, Germany)	
<i>Characterizing the Mechanical Coupling of DE-Elements on a Single Silicone Membrane.....</i>	190
Julian Neu and Sipontina Croce (Saarland University, Germany); Jonas Hubertus (University of Applied Sciences of Saarland, Germany); Günter Schultes (HTWsaar, ZeMA gGmbH, Germany); Stefan Seelecke (Saarland University, Saarbrücken, Germany); Gianluca Rizzello (Saarland University, Germany)	

P1: Poster Session: Various Topics on Actuators

- Investigations of high load actuators based on Shape Memory Alloys..... 194***
 Andrea Böhm (Fraunhofer-Institut für Werkzeugmaschinen und Umformtechnik, Germany);
 Daniel Maiwald and Kenny Pagel (Fraunhofer IWU, Germany); Welf-Guntram Drossel
 (Fraunhofer Institute for Machine Tools and Forming Technology IWU, Germany)
- Design of a pinch mode magnetorheological flow bench: magnetic field analysis 196***
 Michal Kubík (Brno University of Technology, Czech Republic); Janusz Goldasz (BWI
 Group, Technical Center Krakow, Poland); Ondrej Machacek (Brno University of Technology,
 Czech Republic); Bogdan Sapiński (AGH University of Science and Technology, Poland)
- Dielectric elastomer stack actuator modules with integrated electronics and
 encapsulation..... 199***
 Tobias Pointner and Metin Giousouf (Festo SE & Co. KG, Germany); Michael Wegener
 and Silvia Janietz (Fraunhofer IAP, Germany); Selina Gomoll, Antonia Hoppe and
 Christian Splith (FEW Chemicals GmbH, Germany)
- Development of an application-oriented Design Tool for Multilayer Stack Actuators
 based on Dielectric Elastomer Materials..... 205***
 Jana Mertens (Technical University of Berlin, Germany); Jürgen Maas and Ozan Çabuk
 (Technische Universität Berlin, Germany)
- Effect of Heat Treatment and Hydrogen Solution on the Elastic Properties of Titanium..... 209***
 H. T. Uchida, Takaya Sato, Hironori Odaka, Kenta Watanabe, A. Kaneko, Yufeng Sun,
 H. Tsuchiya, Yoshihito Matsumura and A. Tonegawa (Tokai University, Japan)
- Hand-held Device for Force Estimation during Tool Tissue Interaction 213***
 Juliane Mayer, Max B. Schäfer, Jan Liu and Giuliano Antonio Giacoppo (University of
 Stuttgart, Germany); Timo Markert (Wittenstein SE, Germany); Sebastian Matich (Techni-
 sche Universität Darmstadt, Germany); Pascal Brunner and Peter P. Pott (Universität
 Stuttgart, Germany)
- Influence of a fixed twisting zone on Twisted String Actuation 217***
 Giuliano Antonio Giacoppo, Johannes Meiringer, Max B. Schäfer, Michael da Silva,
 Juliane Mayer and Lars Finke (University of Stuttgart, Germany); Peter P. Pott (Universität
 Stuttgart, Germany)
- Magnetically hybridized inkjet-printed and photo-polymerized multi-hydrogel thermo-
 responsive soft gripper 221***
 Alexander Kutscher and Andreas Richter (TU Dresden, Germany)

P2: Poster Session: Electromagnetic Actuators

- Influence of Shaft Material Magnetic Characteristics on Electromagnetic Actuator..... 224***
 Eray Humali (Roketsan Missiles Inc. & Istanbul Technical University, Turkey)
- Pole Pitch Optimization of a Flux Switching Permanent Magnet Linear Machine for Small
 Scale Wave Energy Harvesting..... 228***
 Julius Harms and Thorsten A Kern (Hamburg University of Technology, Germany)

<i>Compact and lightweight linear actuator for handheld medical robotic devices</i>	232
Ralf Gundling (Medical Faculty Mannheim, University Heidelberg, Germany); Peter P. Pott (Universität Stuttgart, Germany); Marcus Götz (MRC Systems GmbH, Germany); Markus Schwarz (Medical Faculty Mannheim, University Heidelberg, Germany)	

<i>Characterisation of Static Pull-In Effect of Hybrid Levitation MicroActuators for Square-Shaped Proof</i>	236
Chun Him Lee (Karlsruhe Institute of Technology, Germany); Sreejith Sasi Kumar (Institute of Microstructure Technology, Germany); Emil R. Mamleyev (Karlsruhe Institute of Technology, Germany); Kirill Poletkin (Karlsruher Institut für Technologie (KIT), Germany)	

<i>Calculation of mutual inductance between circular and arbitrary shaped filaments: Segmentation Method</i>	240
Sreejith Sasi Kumar (Institute of Microstructure Technology, Germany); Chun Him Lee and Emil R. Mamleyev (Karlsruhe Institute of Technology, Germany); Kirill Poletkin (Karlsruher Institut für Technologie (KIT), Germany)	

P3: Poster Session: Micro / Nano Manipulation and Positioning

<i>Directional Behavior of Periodic Honeycombs: towards Lightweight MEMS on SOI Wafers</i>	244
Anna Christina Thewes (Ruhr Universität Bochum & Fakultät für Elektrotechnik und Informationstechnik, Germany); Melvin Jondral and Martin Hoffmann (Ruhr-Universität Bochum, Germany)	

<i>Optimization of Electrostatic Bending-Plate Actuators: Increasing the Displacement and Adjusting the Actuator Stiffness</i>	248
Lisa Schmitt (Ruhr-Universität Bochum, Germany); Philip Schmitt (Ruhr University Bochum, Germany); Martin Hoffmann (Ruhr-Universität Bochum, Germany)	

<i>How to reduce the Pull-in Displacement of Parallel-Plate Actuators</i>	252
Philip Schmitt (Ruhr University Bochum, Germany); Lisa Schmitt and Martin Hoffmann (Ruhr-Universität Bochum, Germany)	

P4: Poster Session: Piezoelectric Actuators / Piezoelectric Motors

<i>Electromechanical Model for Biphasic Piezo Inertia Drive</i>	256
Buelent Delibas and Burhanettin Koc (Physik Instrumente (PI) GmbH & Co. KG, Germany)	

<i>Disc Type Piezoelectric Actuator for Optical Lens Positioning</i>	260
Dalius Mazeika (Vilnius Gediminas Technical University, Lithuania); Piotr Vasiljev (Vytautas Magnus University, Lithuania); Ying Yang (Nanjing University of Aeronautics and Astronautics, China); Andrius Ceponis (Vilnius Gediminas Technical University, Lithuania); Regimantas Bareikis and Arunas Struckas (Vytautas Magnus University, Lithuania); Sergejus Borodinas (Vilnius Gediminas Technical University, Lithuania)	

<i>Ultrasonic Actuator-Driven Medical Fluid Pumps</i>	264
Alexej Wischnewski (Physik Instrumente (PI) & GmbH & Co KG, Germany)	

<i>Design of a 2-phase Piezoelectric Inertia Drive Type Motor</i>	268
Burhanettin Koc and Buelent Delibas (Physik Instrumente (PI) GmbH & Co. KG, Germany)	

<i>A Microchannel Device for Droplet Classification by Manipulation using Piezoelectric Vibrator</i>	272
Takefumi Kanda, Shoko Seo, Yoshiki Ohara and Shuichi Wakimoto (Okayama University, Japan)	
<i>Experimental characterisation of a piezoelectrically actuated force amplifier using optical and self-sensing methods</i>	274
Sonja Müller (Hochschule Furtwangen, Germany); Stefan Rupitsch (Albert-Ludwigs-Universität Freiburg - IMTEK, Germany); Ulrich M Mescheder (Hochschule Furtwangen, Germany)	
<i>FFAA Film Flex Assembled Actuator</i>	
Valerio Zerillo (Yageo, Italy)	

P5: Poster Session: Process Engineering

<i>A New Simple Method for Detecting Biofilms Using Heatable Capacitive Sensor Structures (CSS)</i>	278
Kai-Uwe Zirk, Markus Kemper, Christoph Kolhoff and Patrick Dummeier (University of Applied Science Diepholz, Germany); Manuel Olze (Plümat, Plate & Lübeck GmbH & Co, Germany); Harald Pöttschke (Freelancer, Germany)	
<i>A New Method to Monitoring the Curing of Filler Educts in Fibre Composites</i>	282
Kai-Uwe Zirk, Markus Kemper and Christoph Kolhoff (University of Applied Science Diepholz, Germany); Harald Pöttschke (Freelancer, Germany)	
<i>FEM-assisted design of multi-purpose printed-circuit sensor structures</i>	286
Patrick Dummeier and Kai-Uwe Zirk (University of Applied Science Diepholz, Germany); Harald Pöttschke (Freelancer, Germany)	

P6: Poster Session: Robotics / Micro Robotics / Soft Robotics

<i>Thermosensitive elastomers for shape adaption of soft robotic systems</i>	290
Nina Prem (OTH Regensburg, Germany); Klaus Zimmermann (TU Ilmenau, Germany)	
<i>Design of a Series Elastic Actuator for an Assistive Exoskeleton using Numerical Methods and Gait Data</i>	294
Sander De Groof (KU Leuven, Belgium); Yang Zhang (JUNIA-HEI, France); Peyrodie Laurent (JUNIA, France); Roy Sevit (Thomas More University of Applied Sciences, Belgium); Emmanuel Benjamin Vander Poorten (KU Leuven, Belgium); Erwin Aertbeliën (Katholieke Universiteit Leuven, Belgium); Luc Labey (KU Leuven, Belgium)	
<i>A Low-Cost Hybrid Compact Control Hardware for a Soft Colonoscope</i>	298
Luigi Manfredi (University of Dundee, United Kingdom (Great Britain))	
<i>Design and Development of a Torsion-based Series Elastic Actuator with Nested Encoders for a Wearable Exoskeleton Robot</i>	302
Alihan Kuru, Ozkan Bebek and Barkan Ugurlu (Ozyegin University, Turkey)	

***Topology Optimization-based Design and Development of a Compact Actuator with a High Torque-to-Weight Ratio for Quadrupeds*..... 306**
Sinan Emre, Baris Akin, Erim Can Ozcinar, Baris Balci, Polat Sendur, Ozkan Bebek, Ramazan Unal and Barkan Ugurlu (Ozyegin University, Turkey)

***Improvement of pneumatically driven prosthetic hand for use in daily life* 310**
Ren Yakami and Hironari Taniguchi (Osaka Institute of Technology, Japan);
Shuichi Wakimoto (Okayama University, Japan); Kosuke Morinaga (Hiroshima International University, Japan)

A5: SMA (2)

Chairs: Marco Citro (Saes Getters, Italy), Luigi Manfredi (University of Dundee, United Kingdom (Great Britain))

***Fully coupled simulation of magnetic shape memory alloys under elongating and contracting perpendicular magnetic fields* 314**
Robert Courant and Jürgen Maas (Technische Universität Berlin, Germany)

***Development of Rotatory Decoupled Antagonistic SMA Actuator*..... 318**
Tom Gorges (Intelligent Materials Systems Lab, ZeMA gGmbH, Saarbruecken Germany, Germany); Philipp Molitor (ZeMA gGmbH, Germany); Rouven Britz (Saarland University, Germany); Paul Motzki (ZeMA gGmbH & Saarland University, Germany)

***High-Power and High-Speed SMA Bowling Ball Demonstrator*..... 322**
Philipp Molitor (ZeMA gGmbH, Germany); Rouven Britz (Saarland University, Germany); Paul Motzki (ZeMA gGmbH & Saarland University, Germany)

***A Thermal Energy Harvester Based on Bistable SMA Microactuation*..... 326**
Xi Chen (Karlsruher Institut für Technologie, Germany); Lars Bumke (Kiel University, Germany); Eckhard Quandt (Christian-Albrechts-Universität zu Kiel, Germany); Manfred Kohl (Karlsruher Institut für Technologie (KIT), Germany)

***Miniature Shock Absorber Based on SMA Foil Actuation* 330**
Kiran Jacob (Karlsruhe Institute of Technology, Germany); Nicholas Case (KIT, Germany); Shuichi Miyazaki (University of Tsukuba, Japan); Manfred Kohl (Karlsruher Institut für Technologie (KIT), Germany)

B5: Piezoelectric Actuators

Chair: Franz Schubert (PI Ceramic GmbH, Germany)

***Thermal characterization of passive piezoelectric actuators* 334**
Xenia Y. Ratke (Technische Universität Ilmenau, Germany); Thomas Sattel (Ilmenau University of Technology, Germany)

***Microscale Single Crystal Ultrasonic Actuator for Miniature Optical Systems* 338**
Maxim Wischnewski (Physik Instrumente (PI) GmbH & Co. KG); Alexej Wischnewski (Physik Instrumente (PI) & GmbH & Co KG, Germany); Buelent Delibas (Physik Instrumente (PI) GmbH & Co. KG, Germany); Patrick Pertsch (PI Ceramic GmbH, Germany)

***Expansion of Driving Frequency and Voltage Amplitude Limits and Suppression of Dynamic Characteristic Variations of Piezoelectric Stacked Actuators by Forced Liquid Cooling with Silicon Oil*..... 342**

Rina Nishida, Jianpeng Zhong and Tadahiko Shinshi (Tokyo Institute of Technology, Japan)

***Effect of rotor elasticity on driving characteristics of the ultrasonic motors*..... 346**

Tatsuki Sasamura, Abdullah M Mustafa and Susumu Miyake (The University of Tokyo, Japan); Norio Sashida (Shinsei Corporation, Japan); Takeshi Morita (The University of Tokyo, Japan)

***Damping control using self-sensing signals for coupled piezo actuators* 350**

Bas Jansen (Eindhoven University of Technology & ASML, The Netherlands); Aditya Ananthakrishnan and Hans Butler (Eindhoven University of Technology, The Netherlands); Siep Weiland (Technische Universiteit Eindhoven, The Netherlands)

C5: KOMMMA Session (2)

Chair: Manfred Kohl (Karlsruher Institut für Technologie (KIT), Germany)

Microstructured Stimuli Responsive Hydrogel Actuators

Christine Selhuber-Unkel and Tobias Spratte (Universitätsklinikum Heidelberg, Germany)

***Model Order Reduction of a Nonlinear Electromechanical Beam Actuator by Clustering Nonlinearities*..... 354**

Arwed Schütz (Jade University of Applied Sciences, Germany); Mario Farny (Ruhr-Universität Bochum, Germany); Michael Olbrich (University of Augsburg, Germany); Martin Hoffmann (Ruhr-Universität Bochum, Germany); Christoph Ament (University of Augsburg, Germany); Tamara Bechtold (Jade University of Applied Sciences, Germany)

***Kick & Catch: Coaction of an electrostatic kick and magnetic catch system for the rotation of a sphere* 358**

Mario Farny (Ruhr-Universität Bochum, Germany); Michael Olbrich and Christoph Ament (University of Augsburg, Germany); Martin Hoffmann (Ruhr-Universität Bochum, Germany)

Antagonistic SMA Film Actuators for Folding and Unfolding of Origami-Type Microstructures

Georgino Kaleng Tshikwand (University of Erlangen-Nuremberg, Germany)

***Reduction of the Solenoid Micro-Coil Size as a Path to Transporter Micro-Actuator Array*..... 362**

Emil R. Mamleyev (Karlsruhe Institute of Technology, Germany); Kirill Poletkin (Karlsruher Institut für Technologie (KIT), Germany)

***Calculation of magnetic force between two circular filaments arbitrary oriented in the space by using method of mutual inductance*..... 366**

Kirill Poletkin (Karlsruher Institut für Technologie (KIT), Germany)